

# HEF4060B

## 14-stage ripple-carry binary counter/divider and oscillator

Rev. 10 — 8 November 2021

Product data sheet

### 1. General description

The HEF4060B is a 14-stage ripple-carry counter/divider and oscillator with three oscillator terminals (RS, REXT and CEXT), ten buffered parallel outputs (Q3 to Q9 and Q11 to Q13) and an overriding asynchronous master reset (MR). The oscillator configuration allows design of either RC or crystal oscillator circuits. The oscillator may be replaced by an external clock signal at input RS. In this case, keep the oscillator pins (REXT and CEXT) floating. The counter advances on the HIGH-to-LOW transition of RS. A HIGH level on MR clears all counter stages and forces all outputs LOW, independent of the other input conditions. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of  $V_{DD}$ .

### 2. Features and benefits

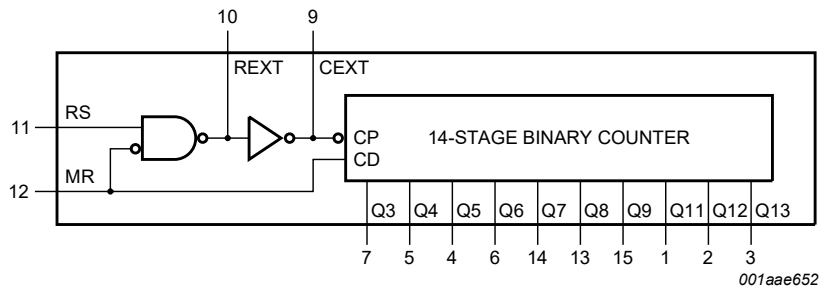
- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- Complies with JEDEC standard JESD 13-B
- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- ESD protection:
  - HBM JESD22-A114F exceeds 2000 V
  - MM JESD22-A115-A exceeds 200 V
- Specified from -40 °C to +85 °C

### 3. Ordering information

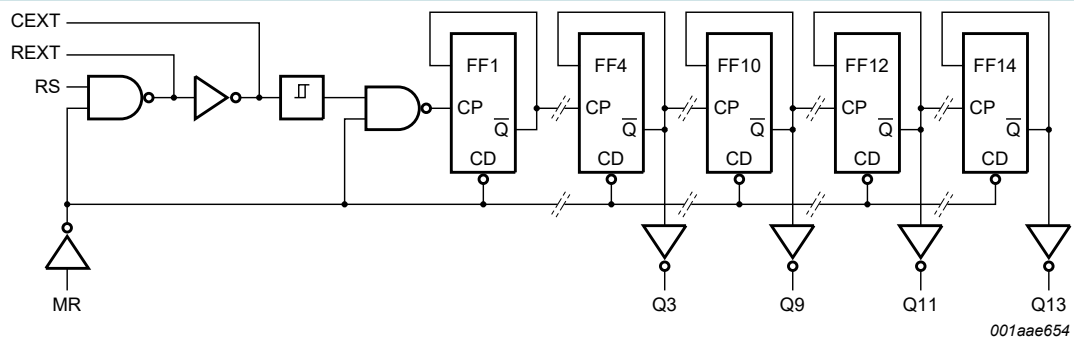
Table 1. Ordering information

Type number	Package			
	Temperature range	Name	Description	Version
HEF4060BT	-40 °C to +85 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1
HEF4060BTT	-40 °C to +85 °C	TSSOP16	plastic thin shrink small outline package; 16 leads; body width 4.4 mm	SOT403-1

#### 4. Functional diagram



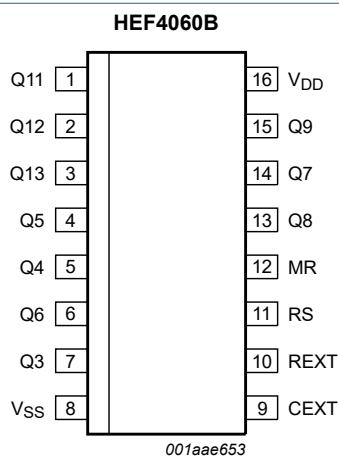
**Fig. 1. Functional diagram**



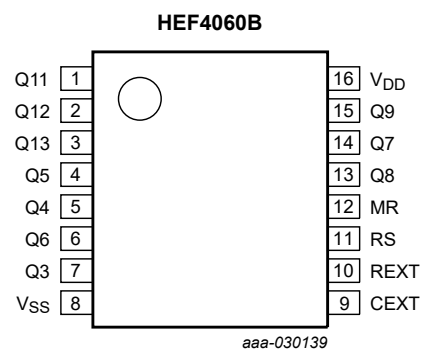
**Fig. 2. Logic diagram**

## 5. Pinning information

## 5.1. Pinning



**Fig. 3. Pin configuration SOT109-1 (SO16)**



**Fig. 4. Pin configuration SOT403-1 (TSSOP16)**

## 5.2. Pin description

Table 2. Pin description

Symbol	Pin	Description
Q11 to Q13	1, 2, 3	counter output
Q3 to Q9	7, 5, 4, 6, 14, 13, 15	counter output
V <sub>SS</sub>	8	ground supply voltage
CEXT	9	external capacitor connection
REXT	10	oscillator pin
RS	11	clock input/oscillator pin
MR	12	master reset
V <sub>DD</sub>	16	supply voltage

## 6. Functional description

Table 3. Function table

H = HIGH voltage level; L = LOW voltage level; ↑ = LOW-to-HIGH clock transition; ↓ = HIGH-to-LOW clock transition.

Input		Output
RS	MR	Q3 to Q9 and Q11 to Q13
↑	L	no change
↓	L	count
X	H	L

## 7. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD</sub>	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	V <sub>I</sub> < -0.5 V or V <sub>I</sub> > V <sub>DD</sub> + 0.5 V	-	±10	mA
V <sub>I</sub>	input voltage		-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	V <sub>O</sub> < -0.5 V or V <sub>O</sub> > V <sub>DD</sub> + 0.5 V	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+85	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> -40 °C to +85 °C	-	500	mW
P	power dissipation	per output	-	100	mW

## 8. Recommended operating conditions

Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{DD}$	supply voltage		3	-	15	V
$V_I$	input voltage		0	-	$V_{DD}$	V
$T_{amb}$	ambient temperature	in free air	-40	-	+85	°C
$\Delta t/\Delta V$	input transition rise and fall rate	input MR				
		$V_{DD} = 5\text{ V}$	-	-	3.75	$\mu\text{s/V}$
		$V_{DD} = 10\text{ V}$	-	-	0.5	$\mu\text{s/V}$
		$V_{DD} = 15\text{ V}$	-	-	0.08	$\mu\text{s/V}$

## 9. Static characteristics

Table 6. Static characteristics

$V_{SS} = 0\text{ V}$ ;  $V_I = V_{SS}$  or  $V_{DD}$  unless otherwise specified.

Symbol	Parameter	Conditions	$V_{DD}$	$T_{amb} = -40\text{ °C}$		$T_{amb} = 25\text{ °C}$		$T_{amb} = 85\text{ °C}$		Unit
				Min	Max	Min	Max	Min	Max	
$V_{IH}$	HIGH-level input voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
$V_{IL}$	LOW-level input voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
$V_{OH}$	HIGH-level output voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
$V_{OL}$	LOW-level output voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
$I_{OH}$	HIGH-level output current	$V_O = 2.5\text{ V}$	5 V	-	-1.7	-	-1.4	-	-1.1	mA
		$V_O = 4.6\text{ V}$	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		$V_O = 9.5\text{ V}$	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		$V_O = 13.5\text{ V}$	15 V	-	-3.6	-	-3.0	-	-2.4	mA
$I_{OL}$	LOW-level output current	$V_O = 0.4\text{ V}$	5 V	0.52	-	0.44	-	0.36	-	mA
		$V_O = 0.5\text{ V}$	10 V	1.3	-	1.1	-	0.9	-	mA
		$V_O = 1.5\text{ V}$	15 V	3.6	-	3.0	-	2.4	-	mA
$I_I$	input leakage current		15 V	-	$\pm 0.3$	-	$\pm 0.3$	-	$\pm 1.0$	$\mu\text{A}$
$I_{DD}$	supply current	$I_O = 0\text{ A}$	5 V	-	20	-	20	-	150	$\mu\text{A}$
			10 V	-	40	-	40	-	300	$\mu\text{A}$
			15 V	-	80	-	80	-	600	$\mu\text{A}$
$C_I$	input capacitance		-	-	-	-	7.5	-	-	pF

## 10. Dynamic characteristics

**Table 7. Dynamic characteristics**

$T_{amb} = 25\text{ }^{\circ}\text{C}$ ;  $V_{SS} = 0\text{ V}$ ;  $C_L = 50\text{ pF}$ ;  $t_r = t_f \leq 20\text{ ns}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	$V_{DD}$	Extrapolation formula[1]	Min	Typ	Max	Unit
$t_{pd}$	propagation delay	RS $\rightarrow$ Q3; see Fig. 5	5 V	[2] $183\text{ ns} + (0.55\text{ ns/pF}) C_L$	-	210	420	ns
			10 V	$69\text{ ns} + (0.23\text{ ns/pF}) C_L$	-	80	160	ns
			15 V	$42\text{ ns} + (0.16\text{ ns/pF}) C_L$	-	50	100	ns
		Qn $\rightarrow$ Qn + 1; see Fig. 5	5 V	-	-	25	50	ns
			10 V	-	-	10	20	ns
			15 V	-	-	6	12	ns
		MR $\rightarrow$ Qn; HIGH to LOW see Fig. 5	5 V	$73\text{ ns} + (0.55\text{ ns/pF}) C_L$	-	100	200	ns
			10 V	$29\text{ ns} + (0.23\text{ ns/pF}) C_L$	-	40	80	ns
			15 V	$22\text{ ns} + (0.16\text{ ns/pF}) C_L$	-	30	60	ns
$t_t$	transition time	see Fig. 5	5 V	[3] $10\text{ ns} + (1.00\text{ ns/pF}) C_L$	-	60	120	ns
			10 V	$9\text{ ns} + (0.42\text{ ns/pF}) C_L$	-	30	60	ns
			15 V	$6\text{ ns} + (0.28\text{ ns/pF}) C_L$	-	20	40	ns
$t_W$	pulse width	minimum width; RS HIGH; see Fig. 5	5 V		120	60	-	ns
			10 V		50	25	-	ns
			15 V		30	15	-	ns
		minimum width; MR HIGH; see Fig. 5	5 V		50	25	-	ns
			10 V		30	15	-	ns
			15 V		20	10	-	ns
$t_{rec}$	recovery time	input MR; see Fig. 5	5 V		160	80	-	ns
			10 V		80	40	-	ns
			15 V		60	30	-	ns
$f_{max}$	maximum frequency	input RS; see Fig. 5	5 V		4	8	-	MHz
			10 V		10	20	-	MHz
			15 V		15	30	-	MHz

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown ( $C_L$  in pF).

[2]  $t_{pd}$  is the same as  $t_{PHL}$  and  $t_{PLH}$ .

[3]  $t_t$  is the same as  $t_{THL}$  and  $t_{TLH}$ .

**Table 8. Power dissipation**

Dynamic power dissipation  $P_D$  and total power dissipation  $P_{tot}$  can be calculated from the formulas shown.  $T_{amb} = 25\text{ }^{\circ}\text{C}$ .

Symbol	Parameter	Conditions	$V_{DD}$	Typical formula for $P_D$ and $P_{tot}$ ( $\mu\text{W}$ )[1]
$P_D$	dynamic power dissipation	per device	5 V	$P_D = 700 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$
			10 V	$P_D = 3300 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$
			15 V	$P_D = 8900 \times f_i + \sum(f_o \times C_L) \times V_{DD}^2$
$P_{tot}$	total power dissipation	when using the on-chip oscillator	5 V	$P_{tot} = 700 \times f_{osc} + \sum(f_o \times C_L) \times V_{DD}^2 + 2 \times C_t \times V_{DD}^2 \times f_{osc} + 690 \times V_{DD}$
			10 V	$P_{tot} = 3300 \times f_{osc} + \sum(f_o \times C_L) \times V_{DD}^2 + 2 \times C_t \times V_{DD}^2 \times f_{osc} + 6900 \times V_{DD}$
			15 V	$P_{tot} = 8900 \times f_{osc} + \sum(f_o \times C_L) \times V_{DD}^2 + 2 \times C_t \times V_{DD}^2 \times f_{osc} + 22000 \times V_{DD}$

[1] Where:

$f_i$  = input frequency in MHz;  $f_o$  = output frequency in MHz;

$C_L$  = output load capacitance in pF;

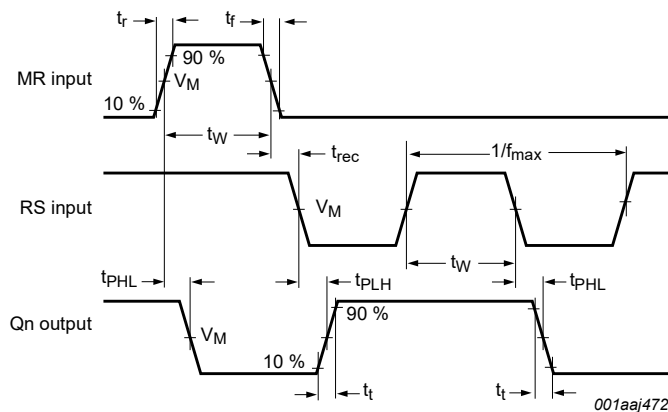
$V_{DD}$  = supply voltage in V;

$\sum(f_o \times C_L)$  = sum of the outputs;

$C_t$  = timing capacitance (pF);

$f_{osc}$  = oscillator frequency (MHz).

## 10.1. Waveforms and test circuit

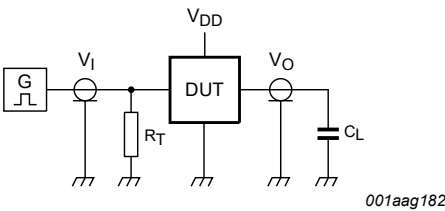


Measurement points are given in [Table 9](#).

**Fig. 5. Waveforms showing propagation delays for MR to Qn and  $\overline{CP}$  to Q0, minimum MR, and  $\overline{CP}$  pulse widths**

**Table 9. Measurement points**

Supply voltage	Input	Output
$V_{DD}$	$V_M$	$V_M$
5 V to 15 V	$0.5V_{DD}$	$0.5V_{DD}$



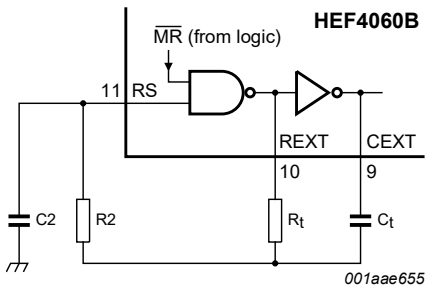
Test data is given in [Table 10](#).  
Definitions for test circuit:  
DUT = Device Under Test;  
 $C_L$  = load capacitance including jig and probe capacitance;  
 $R_T$  = termination resistance should be equal to the output impedance  $Z_o$  of the pulse generator.

Fig. 6. Test circuit for measuring switching times

Table 10. Measurement point and test data

Supply voltage	Input		Load
$V_{DD}$	$V_I$	$t_r, t_f$	$C_L$
5 V to 15 V	$V_{SS}$ or $V_{DD}$	$\leq 20$ ns	50 pF

## 11. RC oscillator



Typical formula for oscillator frequency:  $f_{osc} = \frac{1}{2.3 \times R_t \times C_t}$

Fig. 7. External component connection for RC oscillator

### 11.1. Timing component limitations

The oscillator frequency is mainly determined by  $R_t \times C_t$ , provided  $R_t \ll R_2$  and  $R_2 \times C_2 \ll R_t \times C_t$ . The influence of the forward voltage across the input protection diodes on the frequency is minimized by  $R_2$ . The stray capacitance  $C_2$  should be kept as small as possible. In consideration of accuracy,  $C_t$  must be larger than the inherent stray capacitance.  $R_t$  must be larger than the LOCMOS (Local Oxidation Complementary Metal-Oxide Semiconductor) 'ON' resistance in series with it, which typically is 500  $\Omega$  at  $V_{DD} = 5$  V, 300  $\Omega$  at  $V_{DD} = 10$  V and 200  $\Omega$  at  $V_{DD} = 15$  V.

The recommended values for these components to maintain agreement with the typical oscillation formula are:

- $C_t \geq 100$  pF, up to any practical value,
- $10$  k $\Omega \leq R_t \leq 1$  M $\Omega$ .

11.2. Typical crystal oscillator circuit

In Fig. 8, R2 is the power limiting resistor. For starting and maintaining oscillation a minimum transconductance is necessary.

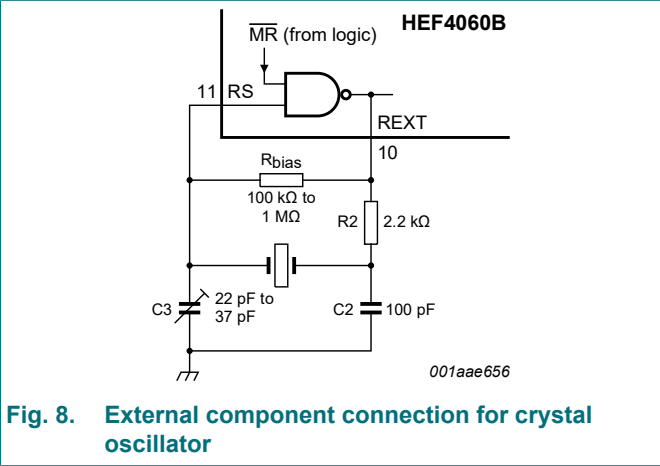


Fig. 8. External component connection for crystal oscillator

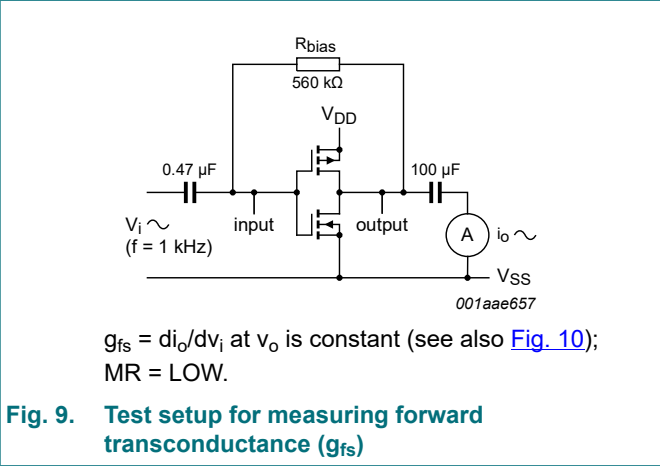


Fig. 9. Test setup for measuring forward transconductance ( $g_{fs}$ )

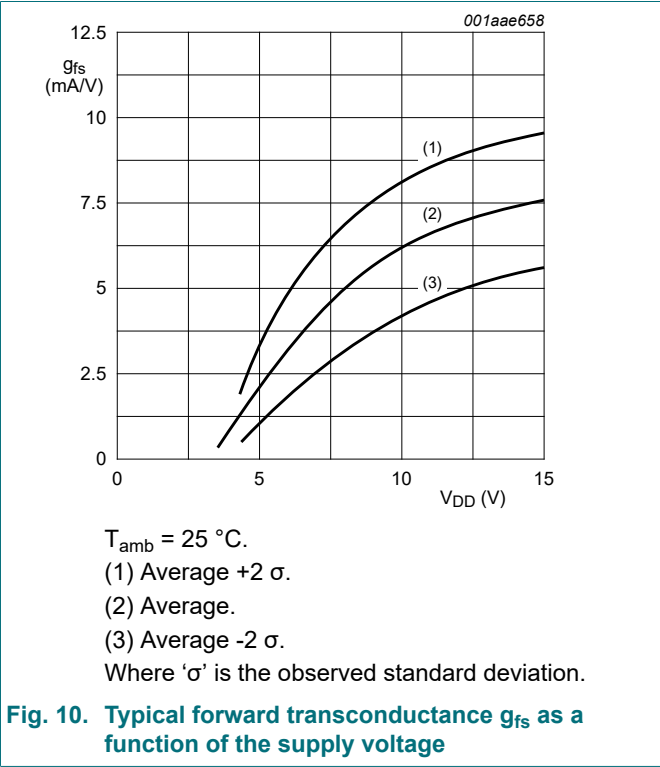


Fig. 10. Typical forward transconductance  $g_{fs}$  as a function of the supply voltage

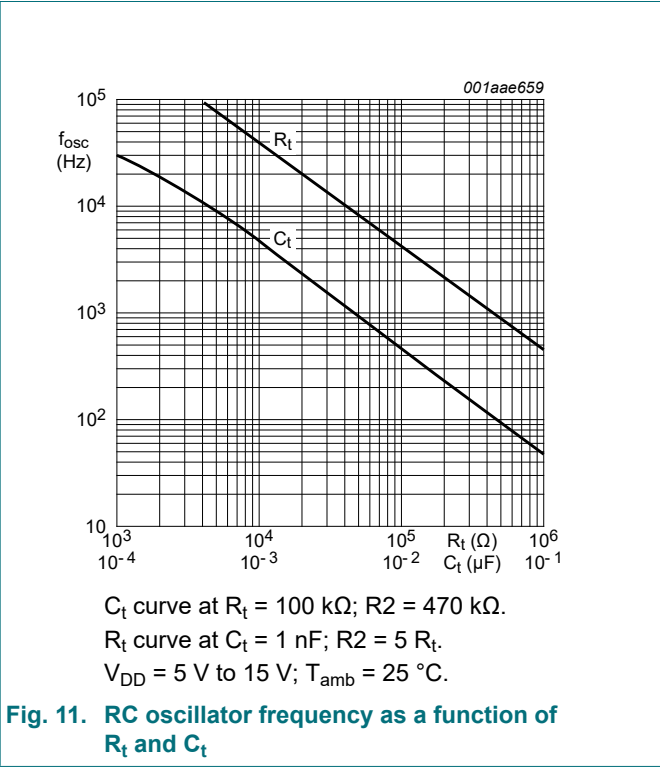
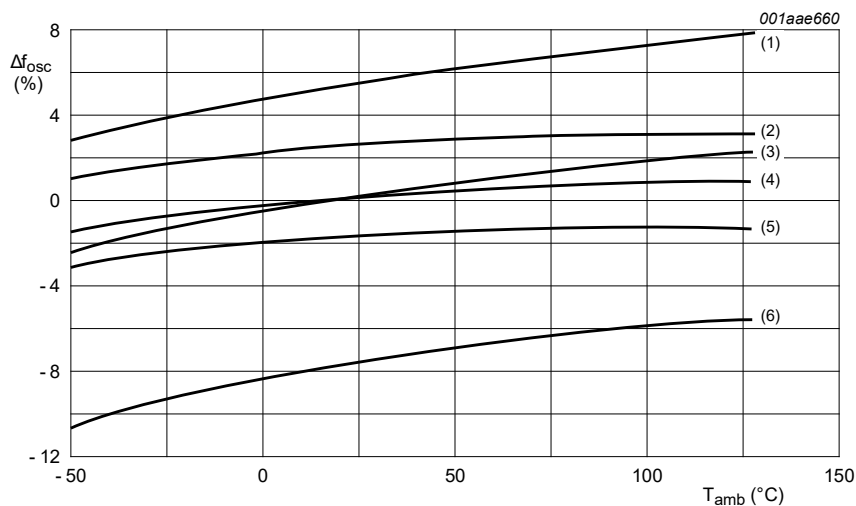


Fig. 11. RC oscillator frequency as a function of  $R_t$  and  $C_t$





Lines (1) and (2):  $V_{DD} = 15\text{ V}$ .

Lines (3) and (4):  $V_{DD} = 10\text{ V}$ .

Lines (5) and (6):  $V_{DD} = 5\text{ V}$ .

Lines (1), (3), (6):  $R_t = 100\text{ k}\Omega$ ;  $C_t = 1\text{ nF}$ ;  $R_2 = 0\text{ }\Omega$ .

Lines (2), (4), (5):  $R_t = 100\text{ k}\Omega$ ;  $C_t = 1\text{ nF}$ ;  $R_2 = 300\text{ k}\Omega$ .

Referenced at:  $f_{osc}$  at  $T_{amb} = 25\text{ }^\circ\text{C}$  and  $V_{DD} = 10\text{ V}$ .

**Fig. 12. Oscillator frequency deviation ( $\Delta f_{osc}$ ) as a function of ambient temperature**

12. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1

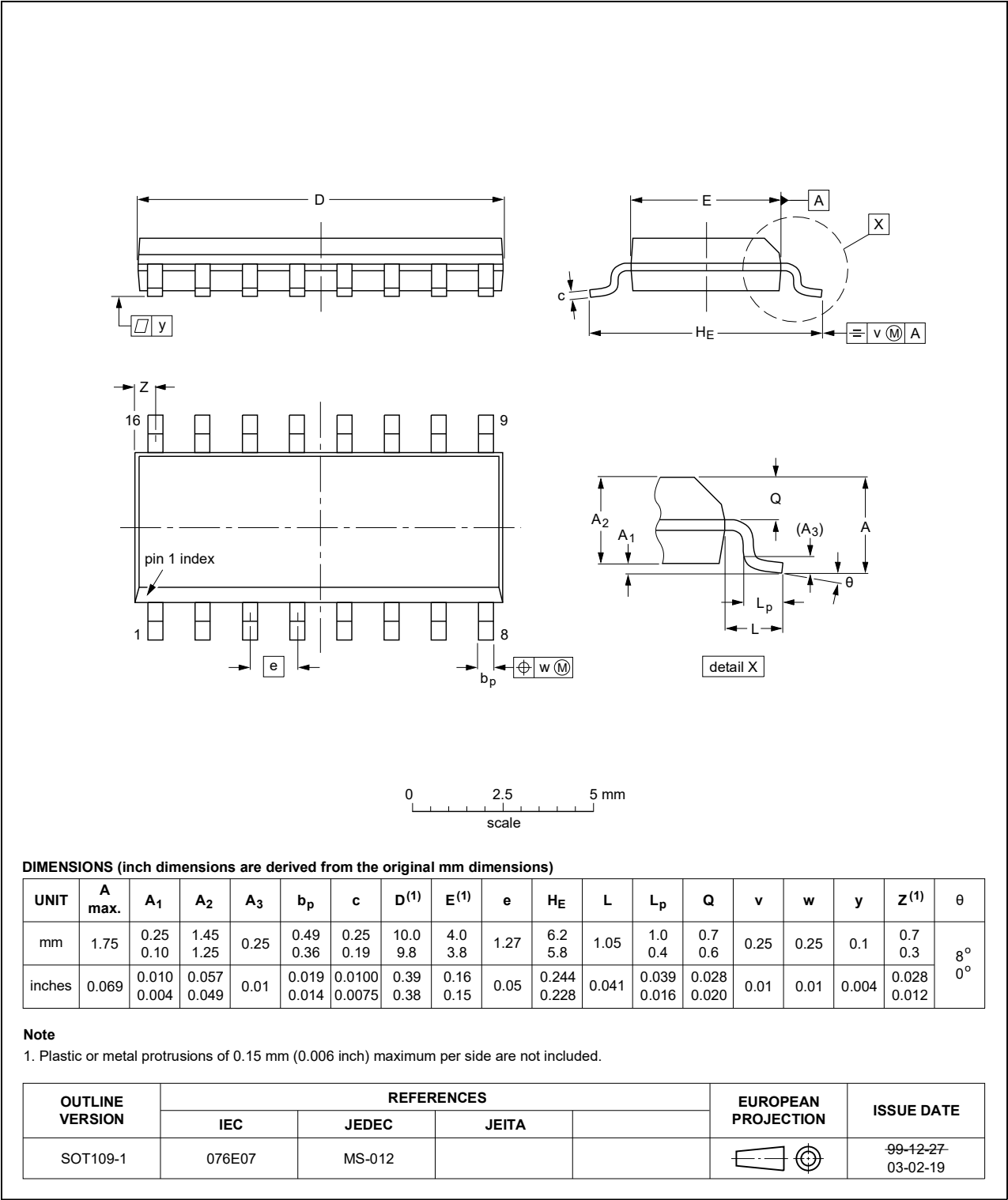


Fig. 13. Package outline SOT109-1 (SO16)

TSSOP16: plastic thin shrink small outline package; 16 leads; body width 4.4 mm

SOT403-1

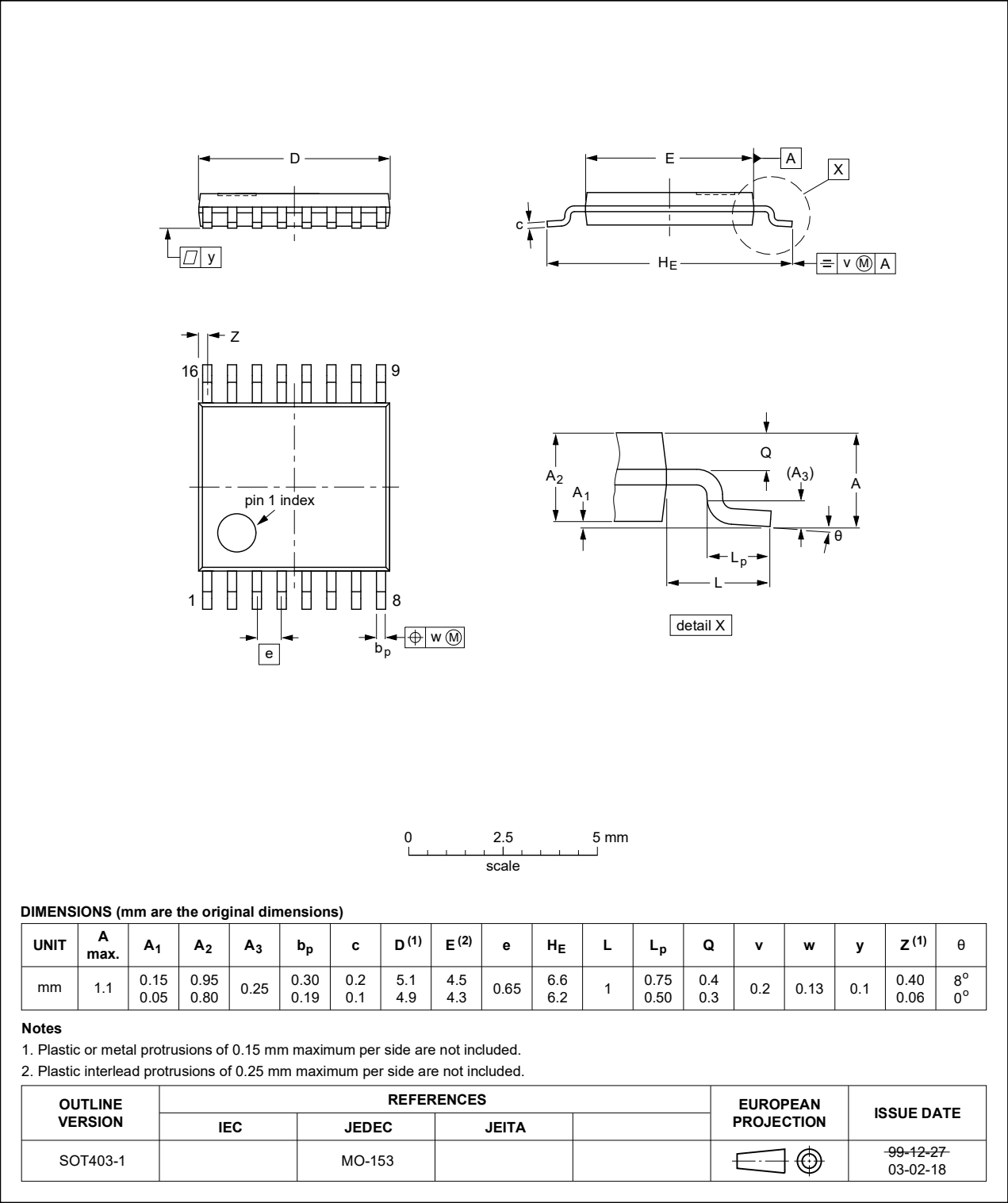


Fig. 14. Package outline SOT403-1 (TSSOP16)

## 13. Abbreviations

Table 11. Abbreviations

Acronym	Description
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MM	Machine Model

## 14. Revision history

Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4060B v.10	20211108	Product data sheet	-	HEF4060B v.9
Modifications:	<ul style="list-style-type: none"> <li>The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia.</li> <li>Legal texts have been adapted to the new company name where appropriate.</li> <li><a href="#">Section 1</a> and <a href="#">Section 2</a> updated.</li> </ul>			
HEF4060B v.9	20190708	Product data sheet	-	HEF4060B v.8
Modifications:	<ul style="list-style-type: none"> <li>Type number HEF4060BTT (SOT403-1/TSSOP16) added.</li> </ul>			
HEF4060B v.8	20160325	Product data sheet	-	HEF4060B v.7
Modifications:	<ul style="list-style-type: none"> <li>Type number HEF4060BP (SOT38-4) removed.</li> </ul>			
HEF4060B v.7	20111116	Product data sheet	-	HEF4060B v.6
Modifications:	<ul style="list-style-type: none"> <li>Legal pages updated.</li> <li>Changes in "General description" and "Features and benefits".</li> <li>Section "Applications" removed.</li> </ul>			
HEF4060B v.6	20110511	Product data sheet	-	HEF4060B v.5
HEF4060B v.5	20091127	Product data sheet	-	HEF4060B v.4
HEF4060B v.4	20090817	Product data sheet	-	HEF4060B_CNV v.3
HEF4060B_CNV v.3	19950101	Product specification	-	HEF4060B_CNV v.2
HEF4060B_CNV v.2	19950101	Product specification	-	-

## 15. Legal information

### Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
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Date of release: 8 November 2021

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